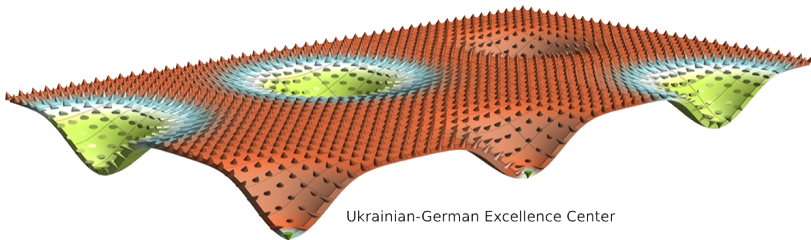


Dynamics of magnetic domain walls in curvilinear wires

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Ukrainian-German Excellence Center

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Outline

1. Phenomenological model of the ferromagnet and general approach for curvilinear wires.
2. Curvature effects in domain wall dynamics.
3. Torsion effects in domain wall dynamics.
4. Conclusions.

Phenomenological model of the ferromagnet

Magnetization equation of motion

$$\frac{\partial \vec{m}}{\partial \bar{t}} = \vec{m} \times \frac{\delta \mathcal{E}}{\delta \vec{m}} + \alpha \vec{m} \times \frac{\partial \vec{m}}{\partial \bar{t}}$$

$\vec{m} = \vec{M}/M_s$ – unit magnetization vector, M_s – saturation magnetization,
 α – Gilbert damping, $\mathcal{E} = E/K$ – dimensionless energy,
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Energy of the ferromagnet

$$E = \underbrace{-A \int_V (\vec{m} \cdot \nabla^2 \vec{m}) d\vec{r}}_{\text{Exchange energy } E_{\text{ex}}} - \underbrace{K \int_V (\vec{m} \cdot \vec{e}_A)^2 d\vec{r}}_{\text{Anisotropy } E_{\text{a}}} - \underbrace{\frac{M_s}{2} \int_V (\vec{m} \cdot \vec{h}_{\text{ms}}) d\vec{r}}_{\text{Magnetostatic energy } E_{\text{ms}}}$$

A – exchange constant, K – anisotropy constant, \vec{h}_{ms} – stray field

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$$\ell = \sqrt{A/K} \sim 10 \text{ nm} - \text{magnetic length}, \quad E_{\text{ms}} \Rightarrow E_{\text{a}}^{\text{eff}} = -K^{\text{eff}} \int_V (\vec{m} \cdot \vec{e}_A)^2 d\vec{r}$$

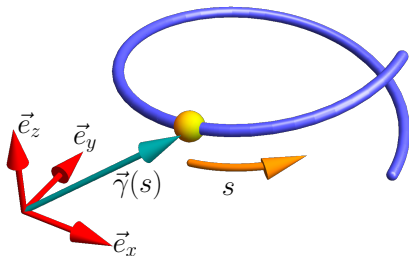
$K_{\text{1D}}^{\text{eff}} = \pi M_s^2$ – effective easy axial anisotropy constant

[Slastikov, Sonnenberg, *Journal of Applied Mathematics* **77**, 220, (2012)]

Exchange energy in curvilinear wire

Frennet-Serret formulas

$\vec{\gamma} = \vec{\gamma}(s)$ – curvilinear wire

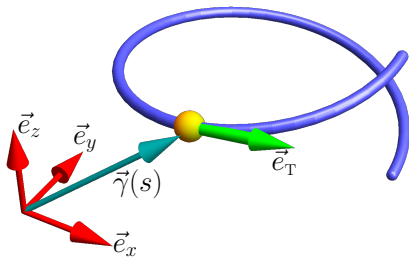


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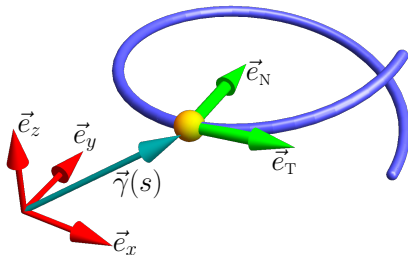


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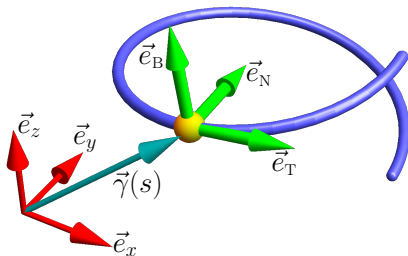


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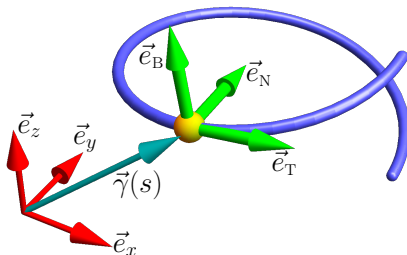
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$$\{\mu, \nu\} = \{T, N, B\}$$

κ – curvature, τ – torsion



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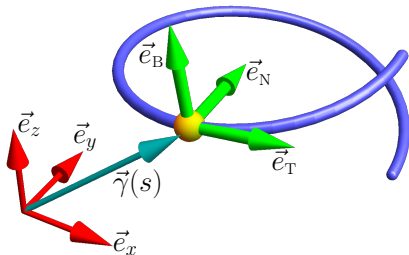
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Exchange energy in curvilinear basis

$$\mathcal{E}_{\text{ex}} = (\vec{e}_{\mu} m_{\mu})' (\vec{e}_{\nu} m_{\nu})'$$

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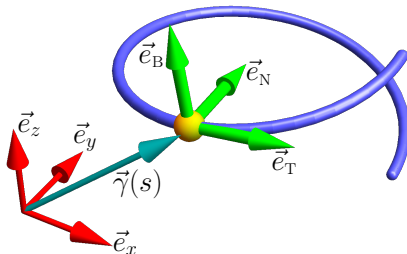
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[Sheka, Kravchuk, Gaididei, J. Phys. A 48, 125202, (2015)]

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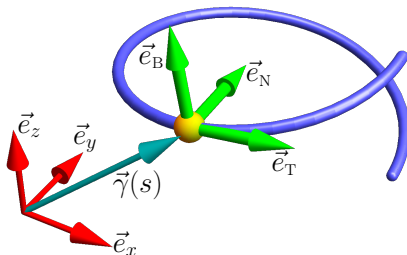
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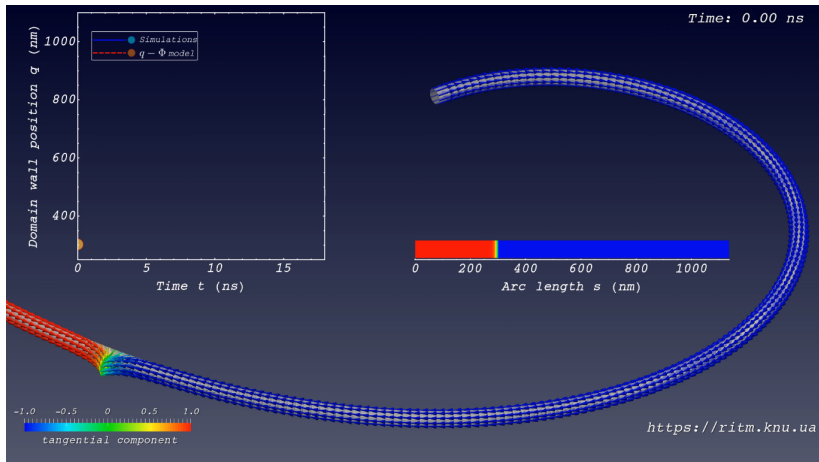
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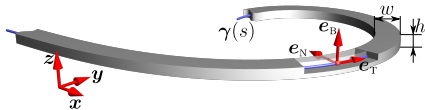
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Curvature induced motion of the domain wall (Cornu spiral as an example)



[Yershov, Kravchuk, Sheka, Pylypovskyi, Makarov, Gaididei, PRB 98, 060409(R) (2018)]

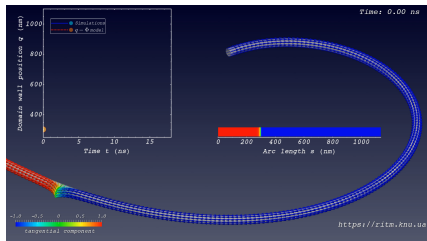
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Energy of the system

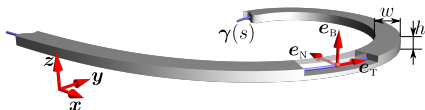
$$\mathcal{E} = \ell^2 \mathcal{E}_{\text{ex}} - (\vec{m} \cdot \vec{e}_T)^2 + \epsilon (\vec{m} \cdot \vec{e}_B)^2$$

$\epsilon > 0$ – anisotropy ratio.



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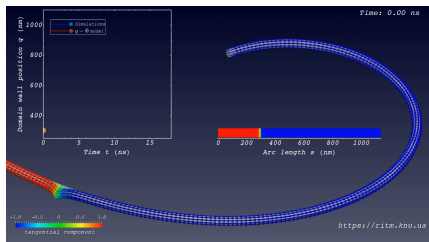
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Collective variable approach (Slonzewski $q - \Phi$ model) \Rightarrow domain wall velocity

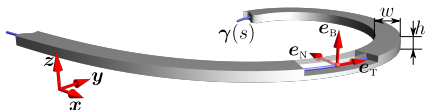
$$V = -pC \frac{\Delta_0 \omega_0}{\alpha} \chi \ell^2$$

$p = \pm 1$ – DW topological charge, $C = \pm 1$ DW chirality, Δ_0 – DW width, $\chi = \kappa' = \text{const}$ – gradient of the curvature.



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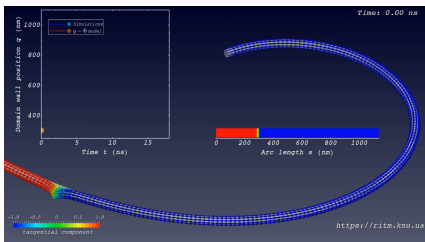
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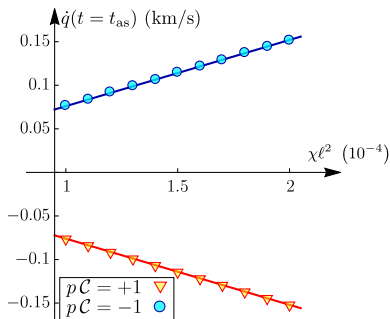
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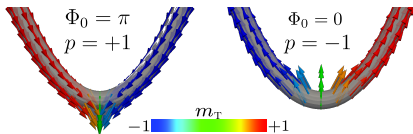
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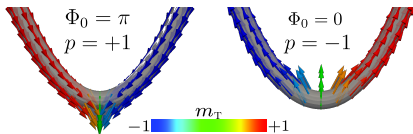
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Domain wall pinning at a local wire bend [$\kappa(\pm\infty) = 0$]



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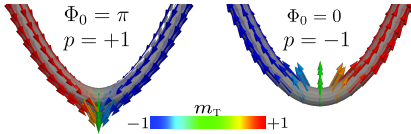
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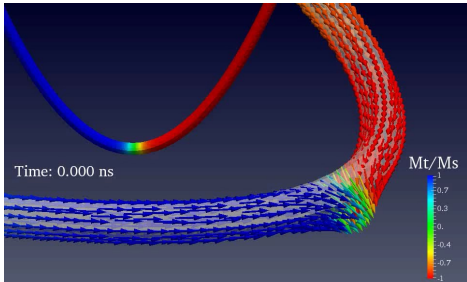


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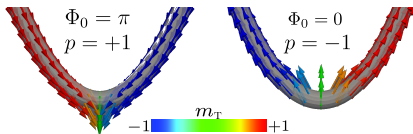
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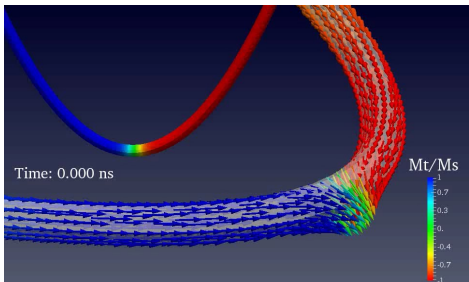


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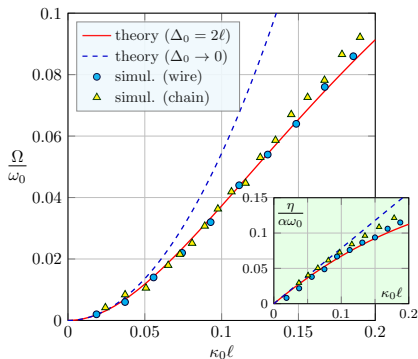
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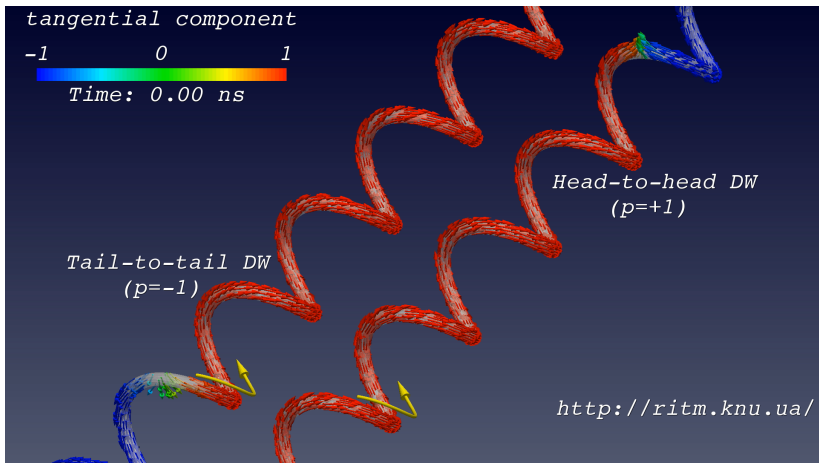
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Torsion effects in current driven domain wall motion



[Yershov, Kravchuk, Sheka, Gaididei, PRB 93, 094418 (2016)]

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Collective variable approach (Slonzewski $q - \Phi$ model) \Rightarrow equations of motion

$$\dot{q} - \alpha p \Delta_0 \dot{\Phi} = u - \pi \kappa \sin \Phi,$$

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$$u_w \approx v_0 \alpha \pi \kappa \ell / (\alpha - \beta + \beta^*), \quad v_0 = \omega_0 \ell$$

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Types of DW motion

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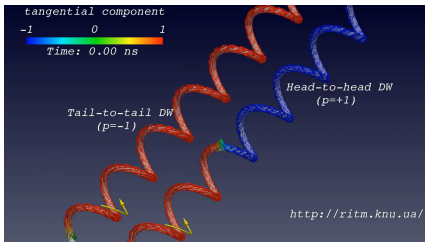
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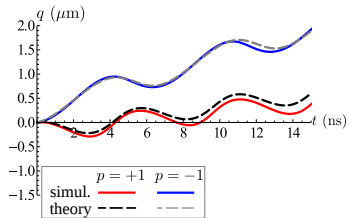
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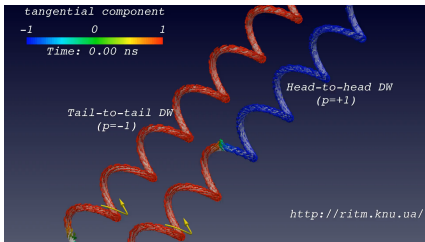
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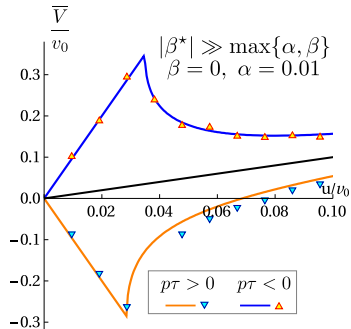
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Thank You For Your Attention!

Coauthors



BITP

- Yuri Gaididei,
- Volodymyr Kravchuk



KNU

- Denis Sheka
- Olexander Pylypovskyi



IFW Dresden

- Volodymyr Kravchuk



HZDR

- Denys Makarov